

Code	Name	Description	DFlag	SNum
A1	Address Matching-House Number	Absolute location point is defined by an automated conversion program based on a user-defined address - primary characteristic used to the define point is the address's HOUSE NUMBER	Y	1
A2	Address Matching-Block Face	Absolute location point is defined by an automated conversion program based on a user-defined address - primary characteristic used to the define point is the city's BLOCK FACE	Y	2
A3	Address Matching-Street Centerline	Absolute location point is defined by an automated conversion program based on a user-defined address - primary characteristic used to the define point is the CENTERLINE of the address's STREET	Y	3
A4	Address Matching-Nearest Intersection	Absolute location point is defined by an automated conversion program based on a user-defined address - primary characteristic used to the define point is the NEAREST INTERSECTION to the identified address	Y	4
A5	Address Matching-Primary Name	Absolute location point is defined by an automated conversion program based on a user-defined address - primary characteristic used to the define point is the address's PRIMARY NAME	Y	5
AO	Address Matching-Other	Absolute location point is defined by an automated conversion program based on a user-defined address - primary characteristic used to the define point is other than one presented in this list	Y	6
AU	Address Matching-Unknown	Absolute location point is defined by an automated conversion program based on a user-defined address - primary characteristic used to the define point is unknown or unspecified	Y	7
C1	Census Block-1990-Centroid	Absolute location point is defined by relating the point of interest to a known Census area where a latitude/longitude has been defined for its centroid - based on the Census Block-1990 data set	Y	8
C2	Census Block/Group-1990-Centroid	Absolute location point is defined by relating the point of interest to a known Census area where a latitude/longitude has been defined for its centroid - based on the Census Block/Group-1990 data set	Y	9
C3	Census Block Tract-1990-Centroid	Absolute location point is defined by relating the point of interest to a known Census area where a latitude/longitude has been defined for its centroid - based on the Census Block Tract-1990 data set	Y	10
CO	Census-Other	Absolute location point is defined by relating the point of interest to a known Census area where a latitude/longitude has been defined for its centroid - based on a Census data set other than one presented in this list	Y	11
CU	Census-Unknown	Absolute location point is defined by relating the point of interest to a known Census area where a latitude/longitude has been defined for its centroid - based on an unknown or unspecified Census data set	Y	12
G1	GPS - submeter accuracy	Absolute location point is defined by a Global Positioning System that computes a latitude/longitude with an accuracy of less than 1 meter	Y	13
G2	GPS - 1 to 5 meter accuracy	Absolute location point is defined by a Global Positioning System that computes a latitude/longitude with an accuracy between 1 and 5 meters	Y	14

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G3	GPS - greater than 5 meter accuracy	Absolute location point is defined by a Global Positioning System that computes a latitude/longitude with an accuracy of greater than 5 meters (excluding methods that can be classified as G4, GPS - partial removal of S/A)	Y	15
G4	GPS - partial removal of S/A	Absolute location point is defined by a Global Positioning System that partially removes error from selective availability offsets (only available to FEDERAL employees), typically computes latitude/longitude with an accuracy of between 6 and 10 meters	Y	16
GU	GPS-Unknown	Absolute location point is defined by Global Positioning System - degree of accuracy is unknown or unspecified	Y	17
I1	Interpolation-MAP, Digitized	Absolute location point is defined by measuring relative distances on a MAP using a digitizer - requires BASIC MAP KNOWLEDGE	Y	18
I2	Interpolation-MAP, Hardcopy	Absolute location point is defined by measuring relative distances on a hardcopy MAP through manual efforts - requires BASIC MAP KNOWLEDGE	Y	19
I3	Interpolation-PHOTO, Digitized	Absolute location point is defined by measuring relative distances on AERIAL PHOTOGRAPHS using a digitizer - requires TRAINED PHOTOINTERPRETER	Y	20
I4	Interpolation-PHOTO, Hardcopy	Absolute location point is defined by measuring relative distances on hardcopy AERIAL PHOTOGRAPHS through manual efforts - requires TRAINED PHOTOINTERPRETER	Y	21
I5	Interpolation-SATELLITE, Digitized	Absolute location point is defined by measuring relative distances on SATELLITE IMAGES using a digitizer - requires TRAINED PHOTOINTERPRETER	Y	22
I6	Interpolation-SATELLITE, Hardcopy	Absolute location point is defined by measuring relative distances on hardcopy SATELLITE IMAGES through manual efforts - requires TRAINED PHOTOINTERPRETER	Y	23
IO	Interpolation-Other	Absolute location point is defined by measuring relative distances on an object that is other than one presented in this list	Y	24
IU	Interpolation-Unknown	Absolute location point is defined by measuring relative distances on an unknown or unspecified object	Y	25
L1	LORAN C	Absolute location point is defined by using receivers and broadcasting stations to calculate the distance from a known point through triangulation - requires knowledge of LORAN receivers, publications, and correction methods	Y	26
P1	Public-Land-Survey-Quartering	Absolute location point is defined by an automated conversion program that relates U.S. Public Land Survey System (PLSS) descriptions to a latitude/longitude - conversion is based on QUARTERING	Y	27
P2	Public-Land-Survey-Footing	Absolute location point is defined by an automated conversion program that relates U.S. Public Land Survey System (PLSS) descriptions to a latitude/longitude - conversion is based on FOOTING	Y	28

<u>Code</u>	<u>Name</u>	<u>Description</u>	<u>DFlag</u>	<u>SNum</u>
S1	Classical Surveying Techniques	Absolute location point is defined by using a traditional method of measuring horizontal distances, elevations, directions, and angles - requires a trained, licensed surveyor	Y	29
Z1	Zipcode-Centroid	Absolute location point is defined as the absolute location point that is associated with the center of a zip code area where the point being identified is located	Y	30
OT	Other	Horizontal method used to define the latitude/longitude is other than one presented in this list	Y	31
UN	Unknown/unspecified	Horizontal method used to define the latitude/longitude is unknown or unspecified	Y	32